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#### APPENDIX I

### Preliminary Engineering Study on a Spin Stabilized Satallite Reconnaiseance System

### I Engineering Analysis of Parameters

#### A. Introduction

- 1. Panoremic essure principle applied to spin stabilised satellite.
- 2. Philosophy of parameter considerations related to simplicity, reliability and availability.
- 3. Reference to Rand Report for certain basic operational requirements and parameters.
- Weblale considerations and recovery techniques (Wobble Analysis Appendix)
- 5. Summery of parameters studied and discussed in following sections.

#### B. Exposure Considerations

- 1. Brightness studies under the following conditions:
  - a. Variations in Latitude
  - b. Variations in time of year
  - c. Veristions in time of day
  - d. Verying brightness during a photographic pass
  - e. Establishing operating limits.

## C. Systems Resolution Considerations

- 1. Operational parameters
- 2. Lens-Film resolution considerations
- 5. Exposure parameters from brightness studies (from Section B-1 above)

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4. Trade-off considerations for operational results in short-time program

#### D. Camera Parameters

- 1. Spin rate and cycling rate.
- 2. Varying exposure by programming.
- 3. Attitude sensing for camera operation.
- b. Nadir recording.
- 5. Synchronisation
- 6. Forward Motion Compensation
- 7. Recovery casestte and capsule study
- 8. Torque reactions and balance.

## B. Photogrammatric Considerations

- 1. Location accuracy
- 2. Distortion considerations
- 3. Discussion of required inputs from camera and/or vehicle
- 4. Requirements for ground support equipment

## F. Test Equipment Studies

- 1. Requirements of parameters to be checked
- 2. Recommended techniques for eccomplishing check-out and test
- Design philosophy for test and check-out equipment, including simulated operating inputs.

#### II Design Considerations

- A. Schematic Functional Diagram
  - 1. Description of cemera operation

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- B. Presentation of Design Layouts
  - 1. Comera configuration in vehicle
  - 2. Cassette design and recovery parameters
  - 3. Camera design and discussion.
- C. General Conclusions